



Physikalisch-Technische Bundesanstalt  
Braunschweig and Berlin  
National Metrology Institute

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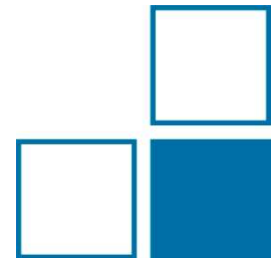
# Uncertainty evaluation in curve fitting and regression problems

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Physikalisch-Technische Bundesanstalt (PTB)  
Braunschweig and Berlin, Germany

BIPM Workshop on Measurement Uncertainty

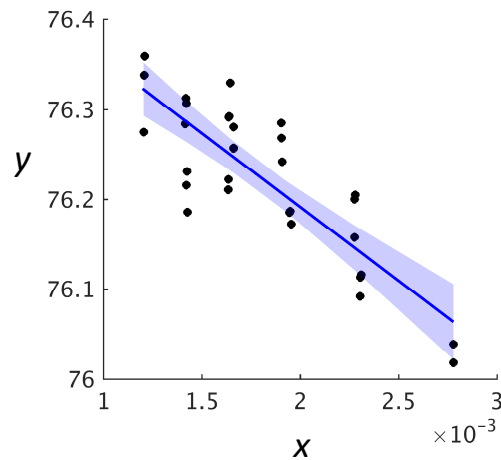
BIPM 15-16 June 2015



# Motivation

- Curve fitting and regression problems relevant in metrology
- GUM and its supplements hardly give guidance
- Least-squares methods often applied
- Bayesian inference provides an alternative

# Regression problem



$$y_i = f_{\theta}(x_i) + \varepsilon_i, i = 1, \dots, n$$

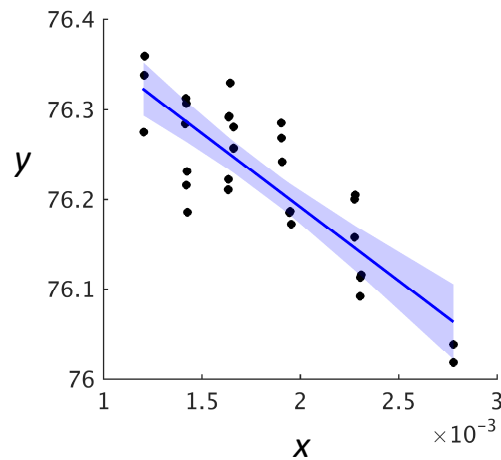
Diagram illustrating the regression model equation  $y_i = f_{\theta}(x_i) + \varepsilon_i$  for  $i = 1, \dots, n$ . Arrows point from the components to their descriptions:

- $y_i$  is labeled **Data**.
- $f_{\theta}(x_i)$  is labeled **Regression function**.
- $\varepsilon_i$  is labeled **Errors**, with an example: e.g.  $\varepsilon_i \sim N(0, \sigma^2)$ .

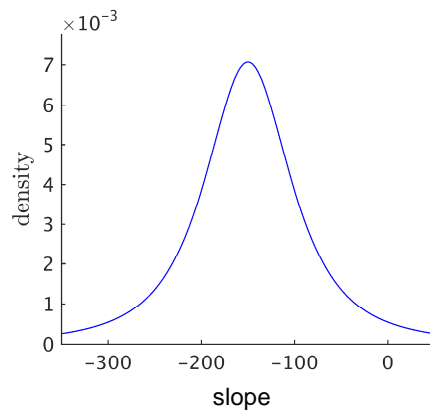
## Measurand

- Regression parameters  $\theta$
- Regression function  $f_{\theta}(x)$
- Prediction of  $x$  from subsequent measurement of  $y$

# Bayesian inference



Prior knowledge



$$y_i = f_{\theta}(x_i) + \varepsilon_i, i = 1, \dots, n$$

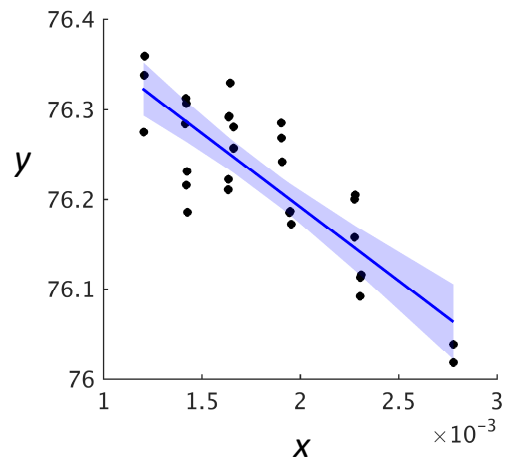
Diagram illustrating the components of the regression model:

- Data (points to  $y_i$ )
- Regression function (points to  $f_{\theta}(x_i)$ )
- Errors (points to  $\varepsilon_i$ )

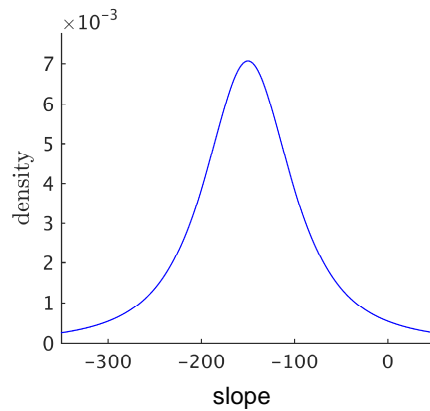
e.g.  $\varepsilon_i \sim N(0, \sigma^2)$

- Previous experiments
- Expert knowledge
- Known relations / constraints

# Bayesian inference



Prior knowledge

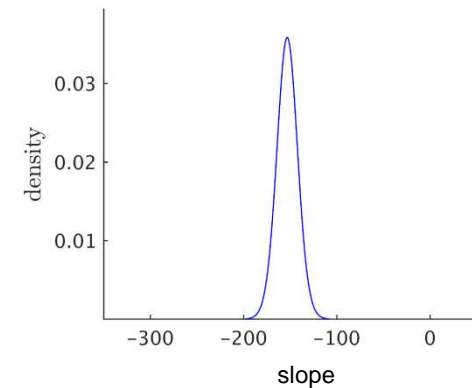


$\times$

Likelihood



Bayes theorem



Posterior distribution

$$y_i = f_{\theta}(x_i) + \varepsilon_i, i = 1, \dots, n$$

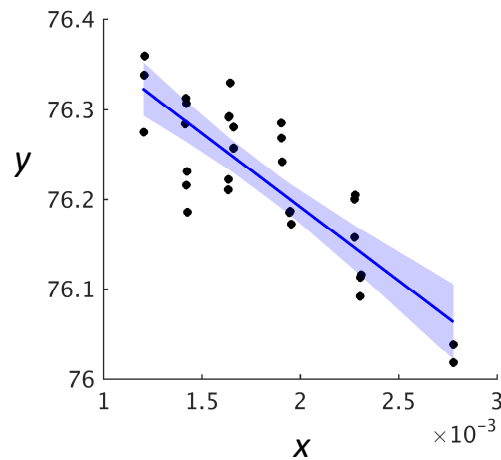
Data

Regression function

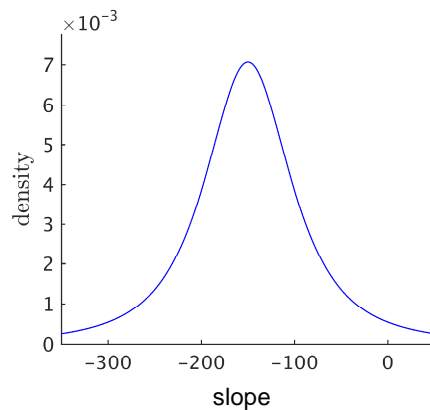
Errors

e.g.  $\varepsilon_i \sim N(0, \sigma^2)$

# Bayesian inference



Prior knowledge

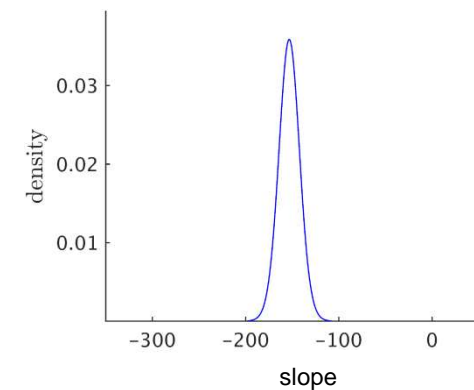


$\times$

Likelihood



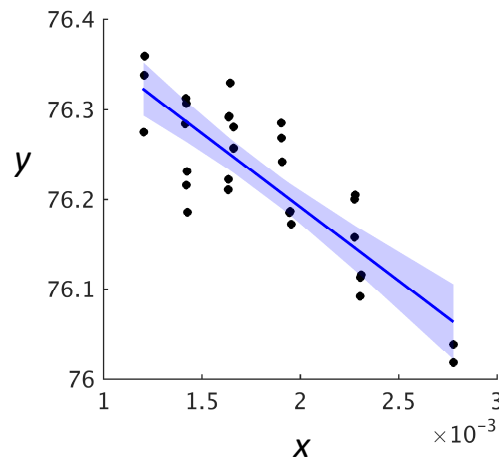
Bayes theorem



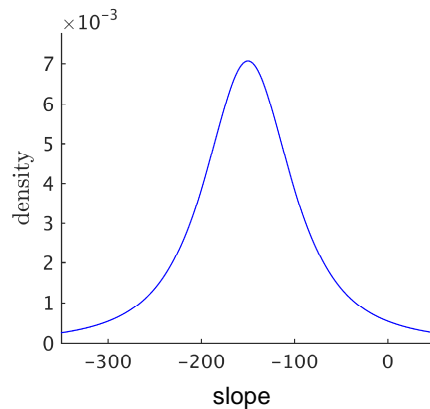
## Posterior distribution

- Comprehensive characterization of uncertainty
- Basis for calculation of estimate and uncertainty
- Transferable (as prior in subsequent analyses)

# Bayesian inference



Prior knowledge



## Posterior distribution

- Comprehensive characterization of uncertainty
- Basis for calculation of estimate and uncertainty
- Transferable (as prior in subsequent analyses)

A O'Hagan and J J Forster (2004) Kendall's advanced theory of statistics, volume 2B: Bayesian inference, Oxford, Oxford University Press

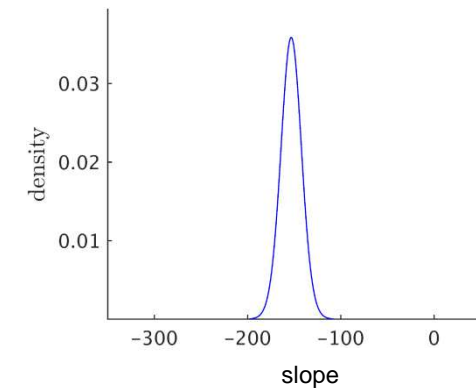
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Likelihood

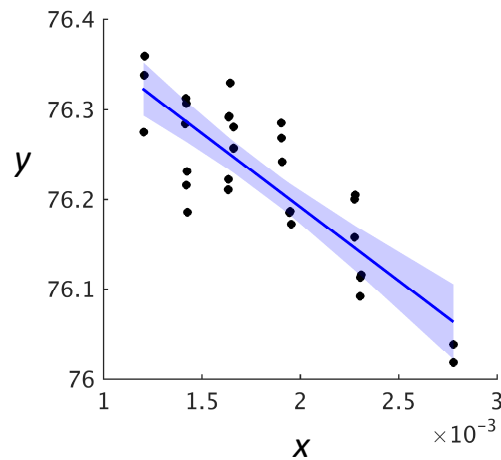


Bayes theorem



Posterior distribution

# Least-squares



$$y_i = f_{\theta}(x_i) + \varepsilon_i, i = 1, \dots, n$$

Diagram illustrating the components of the least-squares model:

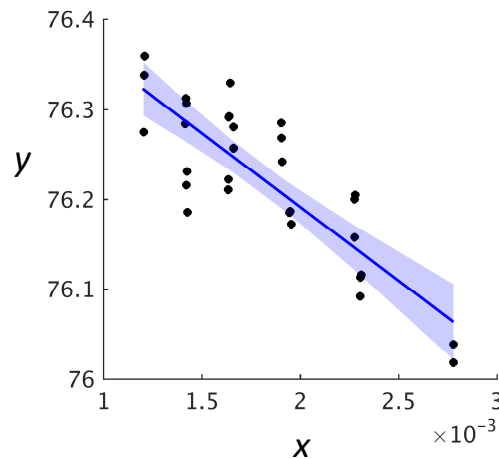
- Data:  $y_i$
- Regression function:  $f_{\theta}(x_i)$
- Errors:  $\varepsilon_i$

e.g.  $\varepsilon_i \sim N(0, \sigma^2)$

$$\hat{\theta} : \min_{\theta} \sum_{i=1}^n (y_i - f_{\theta}(x_i))^2$$



# Least-squares



$$y_i = f_{\theta}(x_i) + \varepsilon_i, \quad i = 1, \dots, n$$

Data
Regression function
Errors

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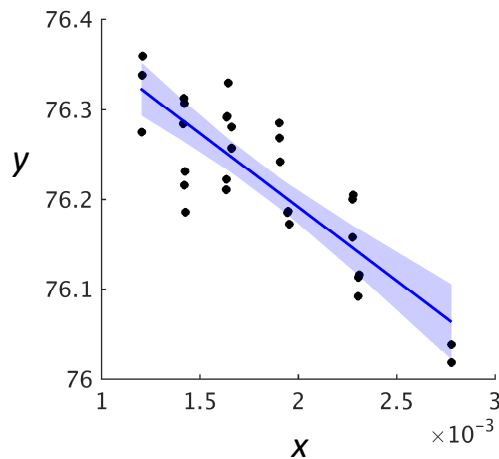
G A F Seber and C J Wild (1989) **Nonlinear regression**, Wiley, New York

N R Draper and H Smith (1998) **Applied regression analysis**, Wiley, New York

$$\mathbf{U}(\hat{\theta}) = \hat{\sigma}^2 (\mathbf{J}^T \mathbf{J})^{-1}, \quad u(\hat{\theta}_{\alpha}) = \sqrt{\hat{\sigma}^2 (\mathbf{J}^T \mathbf{J})_{\alpha\alpha}^{-1}}, \quad \mathbf{J} = \partial f_{\theta}(\mathbf{x}) / \partial \theta$$

$$\frac{\psi^T \hat{\theta}}{\psi^T \mathbf{U}(\hat{\theta}) \psi} \sim t_{n-p}, \quad I_{\theta_{\alpha}} = \hat{\theta}_{\alpha} \pm t_{n-p}^{0.975} u(\hat{\theta}_{\alpha})$$

# Least-squares



$$y_i = f_{\theta}(x_i) + \varepsilon_i, i = 1, \dots, n$$

Diagram illustrating the components of the least-squares model:

- Data (points)
- Regression function ( $f_{\theta}$ )
- Errors ( $\varepsilon_i$ )

e.g.  $\varepsilon_i \sim N(0, \sigma^2)$

$$\hat{\theta} : \min_{\theta} \sum_{i=1}^n (y_i - f_{\theta}(x_i))^2$$

- Cannot include general prior knowledge (but possibly constraints)
- Different meaning of uncertainties than for Bayesian approach
- Typically (much) easier to compute than Bayesian approach
- Provides point estimates and uncertainties – no distribution

# LS combined with GUM-S1/S2 versus Bayesian inference

- Combining LS methods with Supplement 1 (or 2) to the GUM also yields a distribution for the regression parameters
- Is such proceeding equivalent to a Bayesian inference?

# LS combined with GUM-S1/S2 versus Bayesian inference

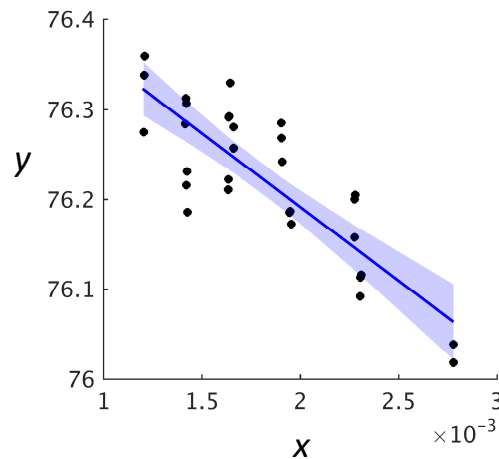
- Combining LS methods with Supplement 1 (or 2) to the GUM also yields a distribution for the regression parameters
- Is such proceeding equivalent to a Bayesian inference?
- In general it is not:
  - No account of prior knowledge (in terms of a distribution)
  - Generally even different to Bayesian inference with noninformative prior

C Elster and B Toman 2011 Bayesian uncertainty analysis for a regression model versus application of GUM Supplement 1 to the least-squares estimate *Metrologia* **48** 233-240

# Normal linear straight line regression

$$y_i = \theta_1 + \theta_2 x_i + \varepsilon_i \quad \varepsilon_i \sim N(0, \sigma^2)$$

<sup>1)</sup>Noninformative prior

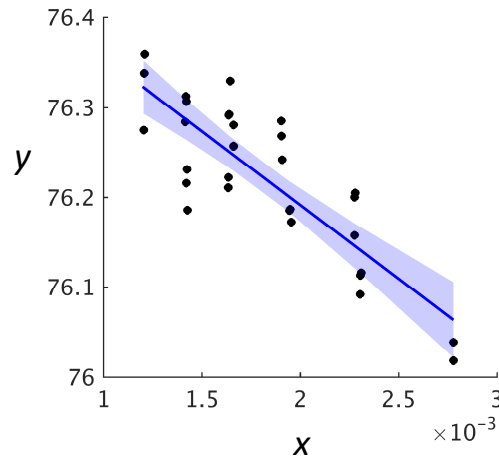


	$\hat{\theta}_2$	$u(\theta_2)$	$I_{0.95}$
LS	-164.6	19.4	$[-204.3, -124.8]$
Bayes <sup>1)</sup>	-164.6	20.1	$[-204.3, -124.8]$

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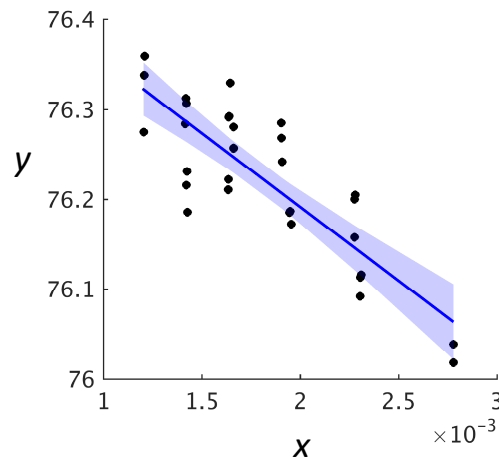
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- Same estimates & intervals
- But different meaning of uncertainties

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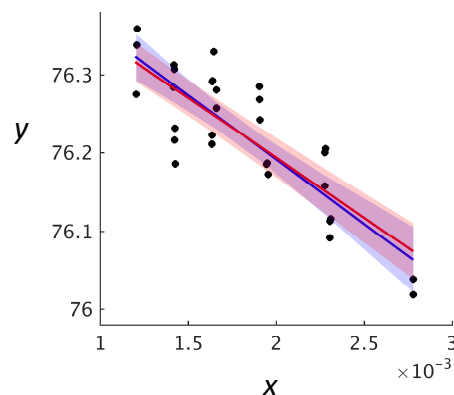
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- Same estimates & intervals
- But different meaning of uncertainties
- Different standard uncertainties

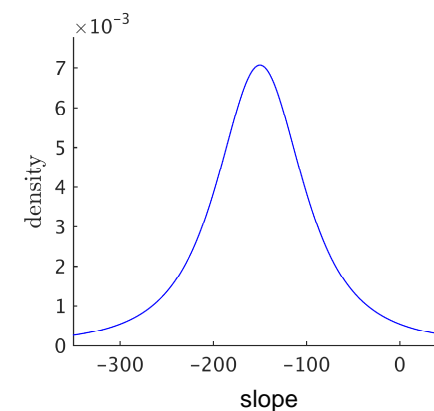
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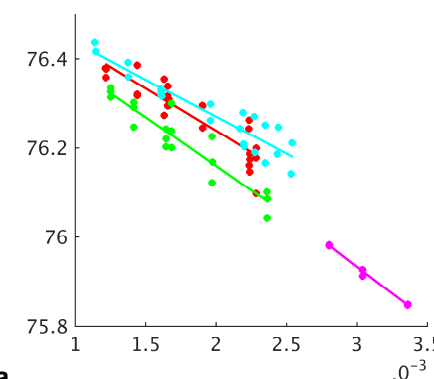
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Prior knowledge from  
previous measurements<sup>1</sup>



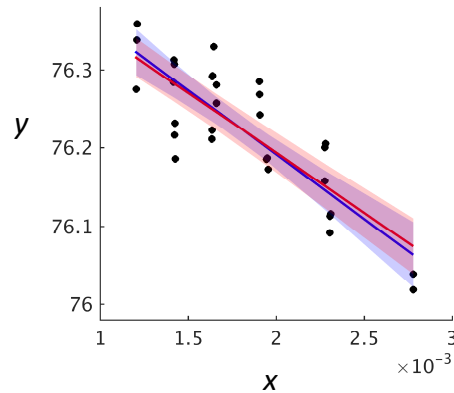
<sup>1</sup>K Klauenberg, G Wübbeler, B Mickan, P M Harris and C Elster  
A tutorial on Bayesian Normal linear regression, submitted to **Metrologia**



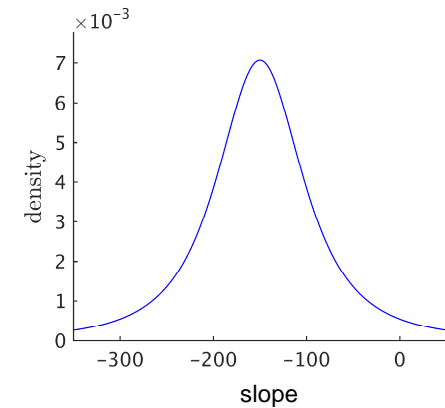
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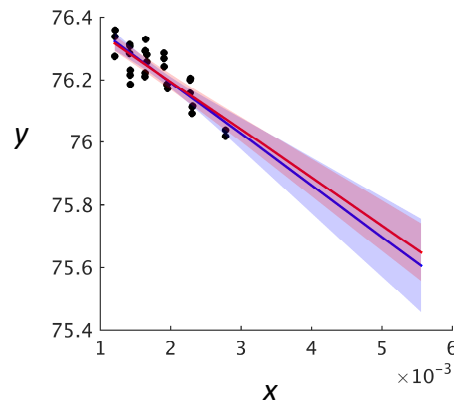


- Different estimates & intervals
- Bayesian inference can result in smaller uncertainties than LS

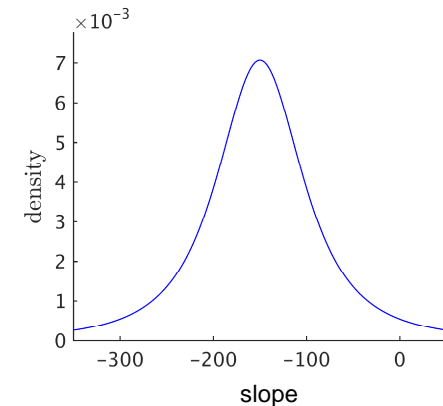
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- Different estimates & intervals
- Bayesian inference can result in smaller uncertainties than LS
- Relevant in particular for prediction beyond the range of data<sup>1,2</sup>

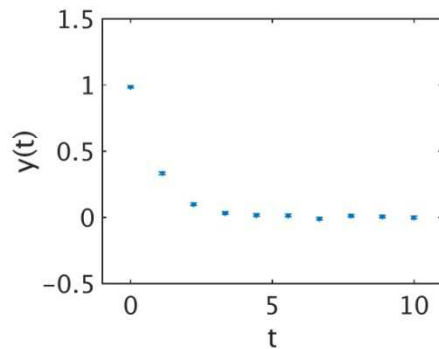
<sup>1</sup>G J P Kok, A M H van der Veen, P M Harris, I M Smith and C Elster (2015) *Bayesian analysis of a flow meter calibration problem*, **Metrologia**, 52, 400-405

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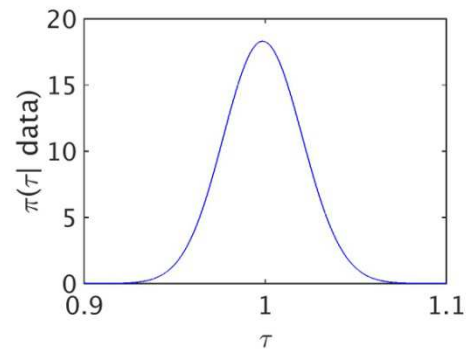
# Nonlinear regression

Model  $y(t_i) = ae^{-t_i/\tau} + \varepsilon_i$ ,  $\varepsilon_i \sim N(0, \sigma^2)$ ,  $a, \sigma$  known,  $\pi(\tau) \propto 1$  ( $0 < \tau < 10$ )

Data



Posterior

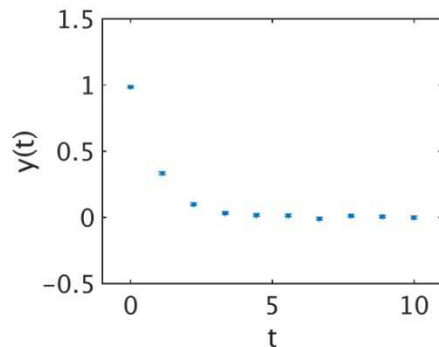


	$\hat{\tau}$	$u(\tau)$	$I_{0.95}$
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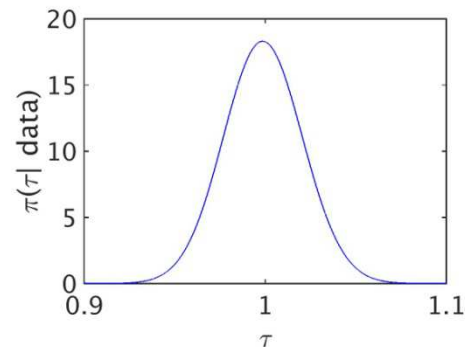
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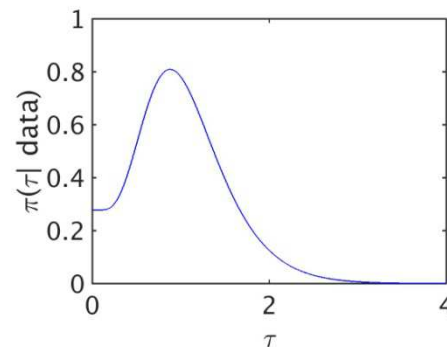
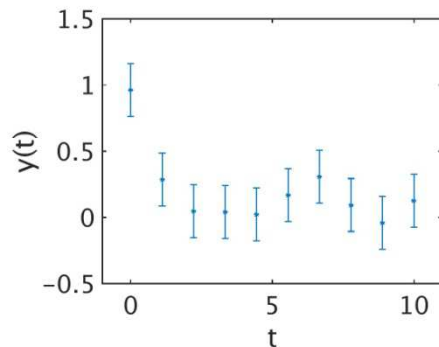
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Bayes	1.00	0.54	[0.09, 2.21]
LS	0.88	0.41	[0.06, 1.70]

For large  $\sigma$  LS may underrate uncertainties due to nonlinearities

# Conclusions

- LS and Bayesian inference different conceptually and typically also numerically
- Calculation of results usually easier for LS than for Bayesian inference

# Conclusions

- LS and Bayesian inference different conceptually and typically also numerically
- Calculation of results usually easier for LS than for Bayesian inference
- LS yields reasonable results when
  - Prior knowledge not available or not really informative, and
  - Simple statistical model appropriate, and
  - No severe nonlinearity in problem
- Bayesian inference advantageous when
  - Prior knowledge available and informative
  - Severe nonlinearity in problem
  - Non-trivial statistical model (e.g. heteroscedastic problem)

# Acknowledgment & reference

- Gerd Wübbeler and Bodo Mickan for preparing figures and providing data
- Part of this work has been funded by the European Metrology Research Program (EMRP) project **NEW 04 Novel mathematical and statistical approaches to uncertainty evaluation**. The EMRP is jointly funded by the EMRP participating countries within EURAMET (European Association of National Metrology Institutes) and the European Union.
- See also talks by Katy Klauenberg, Gertjan Kok, Nicolas Fischer
- C Elster, K Klauenberg, M Walzel, G Wübbeler, P Harris, M Cox, C Matthews, I Smith, L Wright, A Allard, N Fischer, S Cowen, S Ellison, P Wilson, F Pennechi, G Kok, A van der Veen, L Pendrill (2015)  
*A Guide to Bayesian Inference for Regression Problems*, Deliverable of EMRP project NEW04 “Novel mathematical and statistical approaches to uncertainty evaluation” (available at <http://www.ptb.de/emrp/new04-home.html>)

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- A O'Hagan and J J Forster (2004) **Kendall's advanced theory of statistics, volume 2B: Bayesian inference**, Oxford, Oxford University Press
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